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M. Tech 3rd Semester Examination

Digital Signal Processing (NS)

EC-304

Time : 3 Hours

Max. Marks : 100

The candidates shall limit their answers precisely within the answer-book (40 pages) issued to them and no supplementary/continuation sheet will be issued.

Note : Attempt any five questions.

1. (a) Obtain direct form I, Direct form II, cascade, parallel and transposed direct form II structures for the following system:

$$y(n) = y(n-1) - \frac{1}{2}y(n-2) + x(n) - x(n-1) + x(n-2) \quad (10)$$

- (b) Explain the design procedures for FIR & IIR filters. (10)

2. (a) Determine the z-transform of the signal $x(n) = (-1)^n \cos\left(\frac{\pi n}{3}\right) u(n)$. State the properties of z-transform along with their physical significance. (12)

- (b) What is the relationship between Fourier transform and Z-transform? Discuss applications of both the transforms. (8)

3. (a) Compute the N-point DFTs of the signals:

(i) $x(n) = \delta(n - n_0) \quad 0 < n_0 < N$

(ii) $x(n) = e^{\left\{j\frac{2\pi}{N}k_0 n\right\}} \quad 0 \leq n \leq N-1$ (8)

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- (b) Show how linear convolution can be calculated using DFT. (12)

4. (a) What are minimum phase, Maximum phase, and mixed phase systems? (8)

- (b) Determine $|H(\omega)|^2$ for the system

$$y(n) = -0.1y(n-1) + 0.2y(n-2) + x(n) + x(n-1) \quad (12)$$

5. (a) Explain the differences between the discrete sinusoidal signal and continuous time sinusoidal signals in reference to frequency of the sinusoidal signal. Also justify that a discrete frequency is dimension less quantity and have units of that of an angle. (10)

- (b) Explain in detail the Reconstruction filter design. (10)

6. (a) Evaluate the unit step response for the LTI system represented by the impulse response $h(n) = \left(\frac{1}{4}\right)^n u(n)$. (5)

- (b) Find the inverse Fourier transform of

$$X(\omega) = 2 + e^{-j\omega} + 3e^{-j2\omega} + 4e^{-j4\omega}. \quad (5)$$

- (c) State and prove the time shifting and circular convolution properties of Discrete Fourier Transform DFT. (10)

7. (a) Convert the analog filter with the system function

$$H_a(s) = \frac{s + 0.1}{(s + 0.1)^2 + 9}$$

into a digital IIR filter by means of impulse in variance method. (8)

(b) Explain in detail the FIR filter design based on frequency sampling approach. (12)

8. Write short notes on : (any four)

(i) Linear phase filters.

(ii) Sample and Hold circuits.

(iii) Complementary transfer functions.

(iv) LTI discrete time systems.

(v) Methods for computing FFT. (5×4=20)