

16307(D) - 0 DEC 2016

B. Tech 8th Semester Examination

Digital Signal Processing (NS)

EE-424

Time : 3 Hours

Max. Marks : 100

The candidates shall limit their answers precisely within the answer-book (40 pages) issued to them and no supplementary/continuation sheet will be issued.

Note : Attempt five questions in all, selecting one question each from section A, B, C & D. Section-E is compulsory.

SECTION - A

1. (a) Check whether the following systems are linear or non-linear, Causal or non-causal and Time invariant or time-variant.

(i)  $y(n) = a^n u(n)$       (ii)  $y(n) = \log_{10}|x(n)|$       (12)

- (b) Determine whether the following signals are periodic or not? If periodic determine the fundamental period.

(i)  $\sin(10t + 1) - 2\cos(5t - 2)$       (ii)  $\cos\left(\frac{n}{6}\right)\cos\left(\frac{n\pi}{6}\right)$       (8)

2. (a) Determine the z -transform of  $\sin\left(\frac{2\pi n}{8}\right)u[n]$ . Use properties of z-transform to find z- transform

$x_m[n] = \left\{ e^{\frac{-n}{40}} \sin\left(\frac{2\pi n}{8}\right)u[n] \right\}$ .      (12)

2

16307

- (b) Determine the impulse response for the cascade of two linear time-invariant systems having impulse responses

$h_1(n) = \left(\frac{1}{2}\right)^n u(n)$  and  $h_2(n) = \left(\frac{1}{4}\right)^n u(n)$       (8)

SECTION - B

3. (a) Consider the two sequences  
 $x_1(n) = \cos\left(\frac{2\pi}{N}n\right)$ ,  $x_2(n) = \sin\left(\frac{2\pi}{N}n\right)$   
Find the N-point circular convolution of  $x_1(n)$  and  $x_2(n)$ .      (12)

- (b) Discuss overlap-save and overlap-add methods.      (8)

4. (a) Consider the sequence  $x[n] = \delta[n] + 2\delta[n - 2] + \delta[n - 3]$   
(i) Find the four point DFT of  $x[n]$ .  
(ii) If  $y[n]$  is the four point circular convolution of  $x[n]$  with itself, find  $y[n]$  and the four point DFT  $Y[k]$ .      (10)

- (b) Discuss decimation-in-frequency radix-2 FFT algorithm.      (10)

SECTION - C

5. (a) Explain the Frequency sampling method of FIR filter design.      (10)

- (b) Design a FIR filter to meet the following specifications  
(i) Pass-band edge:  $F_p = 2\text{KHz}$   
(ii) Stop-band edge:  $F_s = 5\text{KHz}$   
(iii) Pass band attenuation  $A_p = 2\text{dB}$   
(iv) Stop band attenuation  $A_s = 42\text{dB}$   
(v) Sampling Frequency:  $F_t = 20\text{KHz}$       (10)

6. (a) For the analog transfer function,  $H(s) = \frac{2}{s^2 + 3s + 2}$ , determine  $H(z)$  using bilinear transformation if (a)  $T=1$  second and (b)  $T=0.1$  second. (12)
- (b) Discuss the various methods of IIR filter design. (8)

#### SECTION - D

7. (a) Obtain Haar transformation matrix for  $N=8$ , where  $N$  is the order of matrix. (10)
- (b) Discuss one practical application of wavelets. (10)
8. (a) Explain the various addressing modes used in DSP processors. (12)
- (b) Explain the MAC unit and barrel shifters of DSP processors. (8)

#### SECTION - E

9. (a) State initial and final value theorem for z-transform.
- (b) What is the causality and stability conditions for LTI system in terms of impulse response of system?
- (c) List the properties of convolution.
- (d) Compare FIR and IIR filters.
- (e) What are the factors that influence the choice of structure for the realization of LTI system?
- (f) What is FFT and why is it needed?
- (g) What is aliasing problem in impulse invariance method of designing digital filters?

- (h) What do you understand by linear phase response?
- (i) What is short time Fourier transform?
- (j) What is difference between Von Neumann and Harvard architecture? (2×10=20)